

Pendule paramétrique

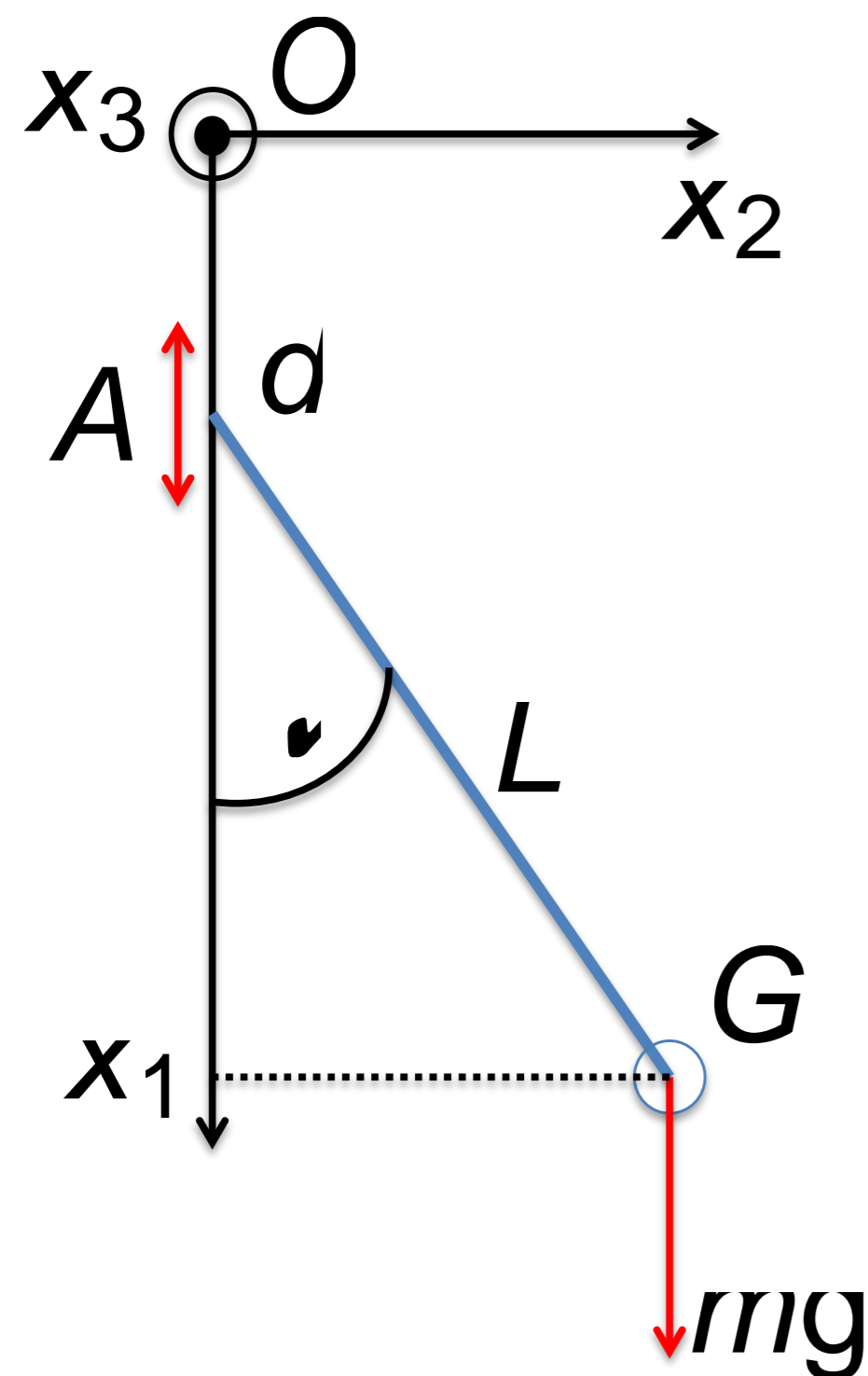
Mécanique, cours 28.2

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Pendule paramétrique

- Equation du mouvement par la méthode de Lagrange
- Equation de Mathieu
- Fonctions propres
- Domaines de stabilité

Pendule forcé : méthode de Lagrange



$$x_1 = d + L \cos \theta$$

$$x_2 = L \sin \theta$$

$$\dot{x}_1 = \dot{d} - L\dot{\theta} \sin \theta$$

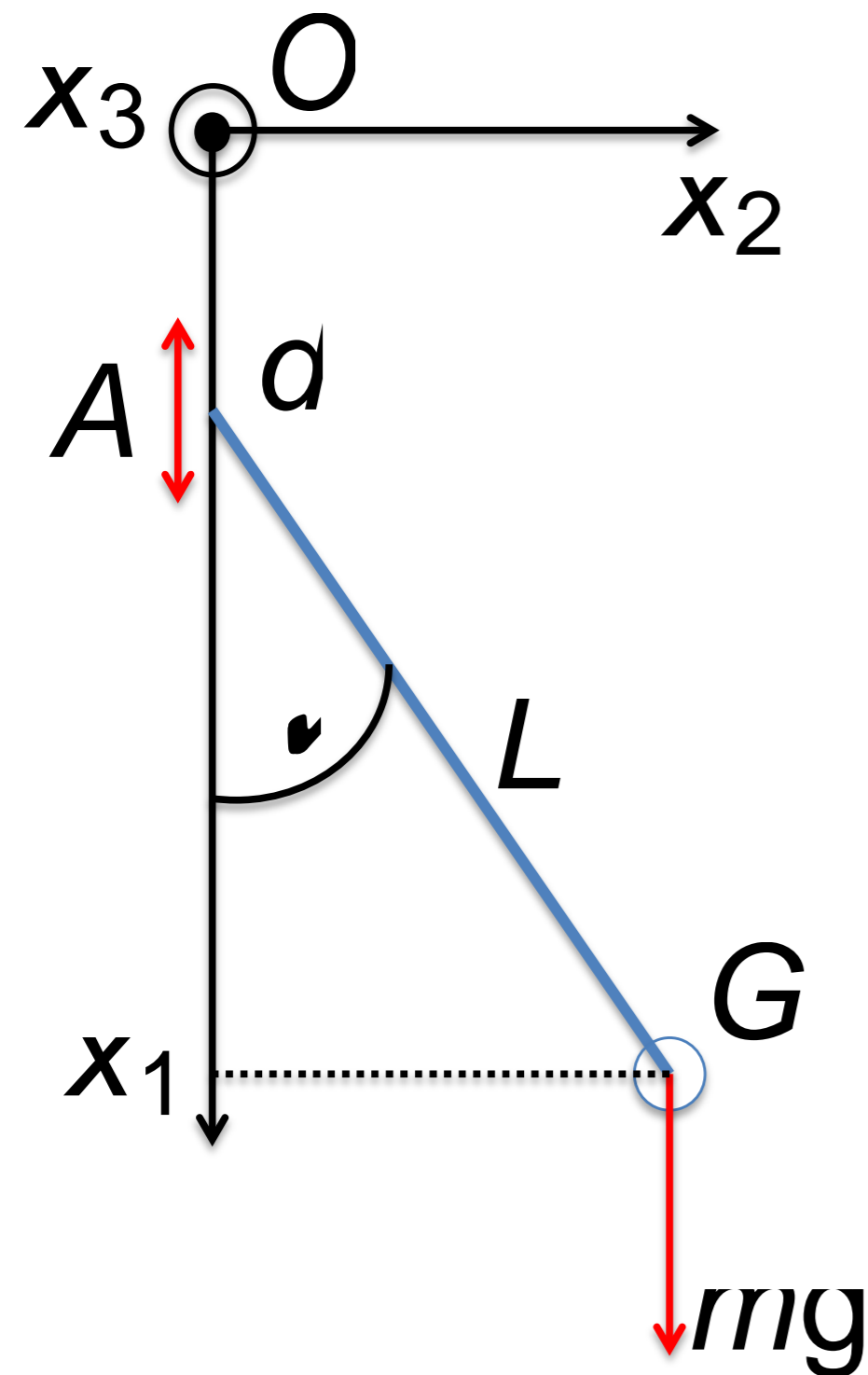
$$\dot{x}_2 = L\dot{\theta} \cos \theta$$

$$T = \frac{1}{2} m \left(\dot{d}^2 - 2\dot{d}L\dot{\theta} \sin \theta + L^2 \dot{\theta}^2 \right)$$

$$V = -mg(d + L \cos \theta)$$

$$L = \frac{1}{2} m \dot{d}^2 - m \dot{d} L \dot{\theta} \sin \theta + \frac{1}{2} m L^2 \dot{\theta}^2 + mgd + mgL \cos \theta$$

Pendule forcé : équation du mouvement



$$L = \frac{1}{2}m\dot{d}^2 - m\dot{d}L\dot{\theta} \sin \theta + \frac{1}{2}mL^2\dot{\theta}^2 + mgd + mgL \cos \theta$$

$$\frac{\partial L}{\partial \dot{\theta}} = -m\dot{d}L \sin \theta + mL^2\dot{\theta}$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) = -m\ddot{d}L \sin \theta - m\dot{d}\dot{\theta} \cos \theta + mL^2\ddot{\theta}$$

$$\frac{\partial L}{\partial \theta} = -m\dot{d}L\dot{\theta} \cos \theta - mgL \sin \theta$$

$$\ddot{\theta} + \frac{g}{L} \sin \theta - \frac{\ddot{d}}{L} \sin \theta = 0$$

Equation de Hill

$$\ddot{\theta} + \frac{g}{L} \sin \theta - \frac{\ddot{d}}{L} \sin \theta = 0$$

$$d = d_0 \cos(2\Omega t)$$

$$\theta \rightarrow 0$$

$$\ddot{\theta} + \left(\frac{g}{L} + \frac{4d_0\Omega^2}{L} \cos(2\Omega t) \right) \theta = 0$$

$$\ddot{x} + G(t)x = 0 \quad x = L\theta$$

$$\text{période : } \tau = \frac{\pi}{\Omega}$$

$$\ddot{\theta} + \left(\frac{g}{L} + \frac{4d_0\Omega^2}{L} \cos(2\Omega t) \right) \theta = 0$$

$$y'' + (p - 2q \cos 2\bar{t}) y = 0$$

$$\bar{t} = \Omega t$$

$$p = \frac{g}{L\Omega^2} \qquad q = \frac{-2d_0}{L}$$

$$-\frac{p}{2} = \frac{q^2}{4 - p - \frac{q^2}{16 - p - \frac{q^2}{36 - p - \frac{q^2}{(\dots)}}}}$$

$$\frac{A_2}{A_0} = \frac{p}{q}$$

$$\frac{A_2}{A_0} = \frac{-q}{4 - p + q \frac{A_4}{A_2}}$$

$$\frac{A_{2r}}{A_{2r-2}} = \frac{-q}{4r^2 - p + q \frac{A_{2r+2}}{A_{2r}}}$$

$$y'' + (p - 2q \cos 2\bar{t}) y = 0$$

chercher une solution de période π :

$$\bar{e}_1(\bar{t}) = \sum_{r=0}^{\infty} A_{2r} \cos 2r\bar{t}$$

$$2 \cos 2r\bar{t} \cos 2\bar{t} = \cos(2r + 2)\bar{t} + \cos(2r - 2)\bar{t}$$

$$2 \sin 2r\bar{t} \cos 2\bar{t} = \sin(2r + 2)\bar{t} + \sin(2r - 2)\bar{t}$$

$$pA_0 - qA_2 = 0$$

$$(p - 4)A_2 - q(2A_0 + A_4) = 0$$

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$$(p - 4r^2)A_{2r} - q(A_{2r-2} + A_{2r+2}) = 0$$

autres solutions de période π :

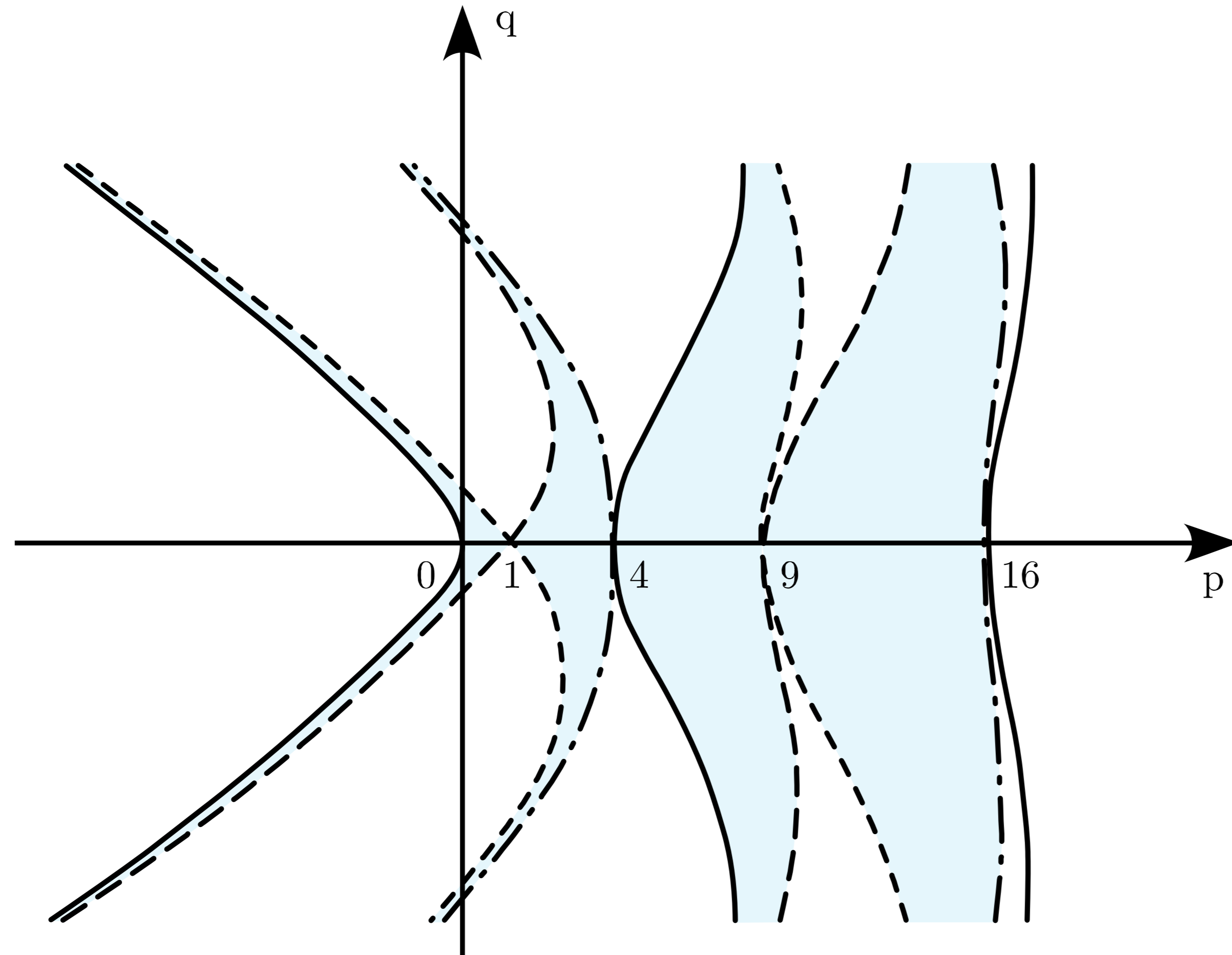
$$\bar{e}_2(\bar{t}) = \sum_{r=0}^{\infty} B_{2r+2} \sin(2r + 2)\bar{t}$$

solutions de période 2π :

$$\bar{e}_3(\bar{t}) = \sum_{r=0}^{\infty} A_{2r+1} \cos(2r + 1)\bar{t}$$

$$\bar{e}_4(\bar{t}) = \sum_{r=0}^{\infty} B_{2r+1} \sin(2r + 1)\bar{t}$$

Relation de dispersion $p(q)$ des fonctions propres



$$y'' + (p - 2q \cos 2\bar{t}) y = 0$$

$$q = \frac{-2d_0}{L}$$

$$p = \frac{g}{L\Omega^2}$$